

Augmenting Paths

Math 482, Lecture 25

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Lecture plan

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- 1 Describe a simple greedy algorithm that tries to find a max flow.
- 2 See it get stuck.
- 3 Make the algorithm more powerful.

Directed s, t -paths

Definition

In a network, a *directed path* from s to t is a sequence

$$s, v_1, v_2, \dots, v_k, t$$

where $v_1, v_2, \dots, v_k \in N$ and $(s, v_1), (v_1, v_2), \dots, (v_k, t) \in A$.

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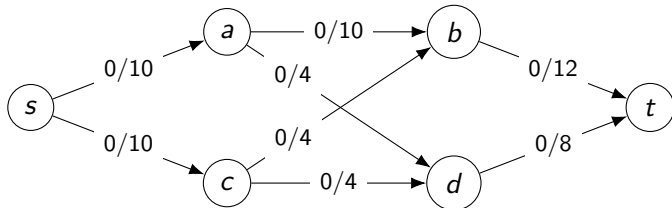
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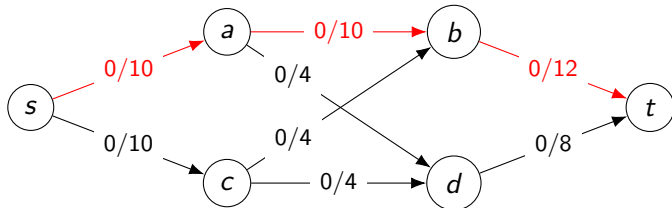
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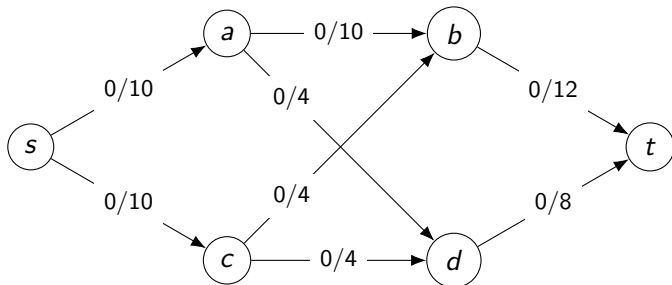
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Example: **directed path** $s \rightarrow a \rightarrow b \rightarrow t$



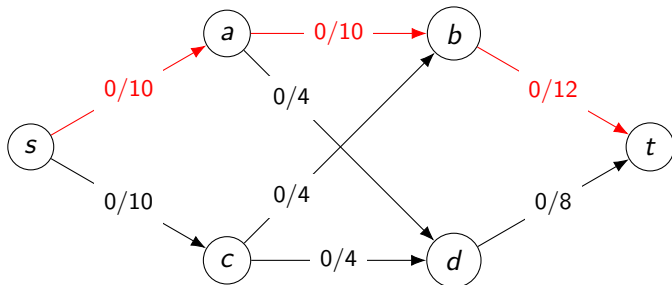
Using a directed path

Whenever we have a directed path from s to t and all arcs along the path are below capacity, we can use it to increase the flow.



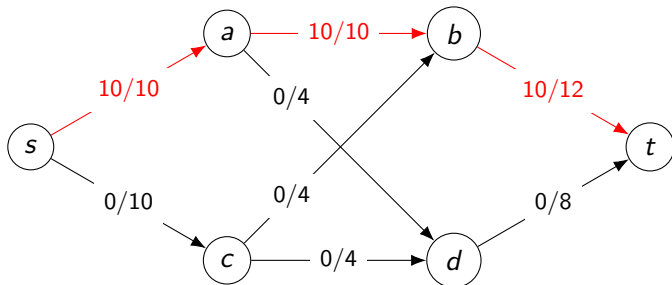
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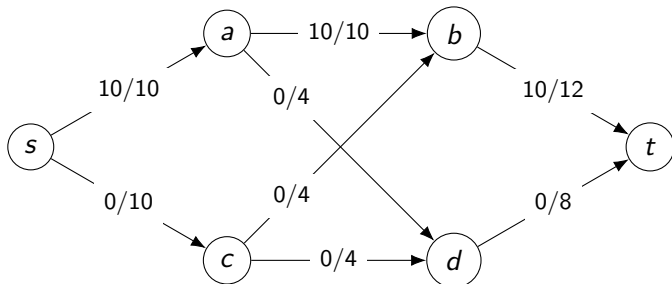
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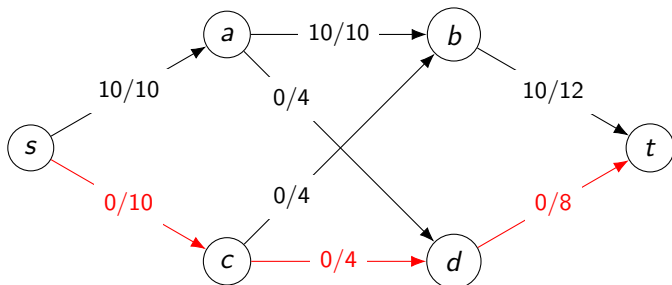
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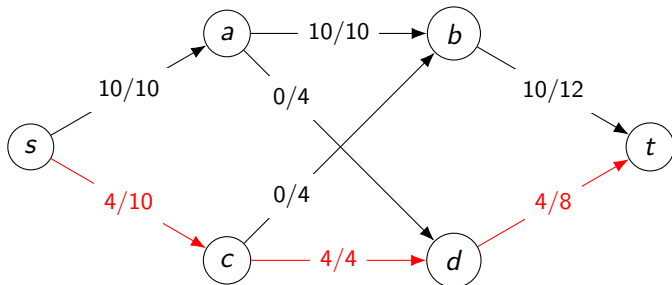
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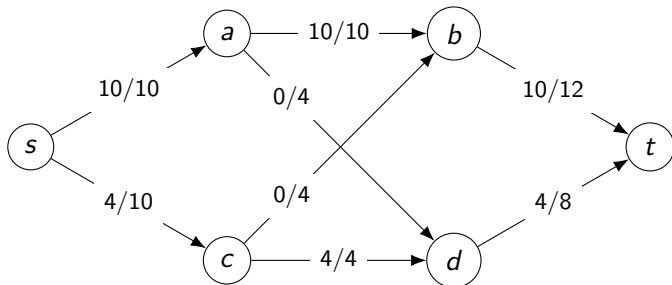
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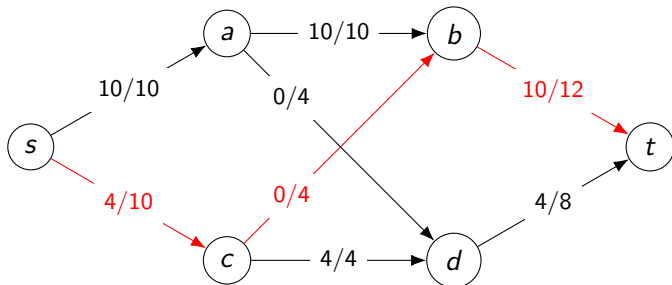
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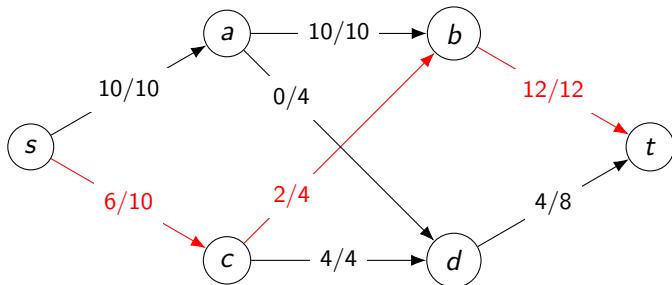
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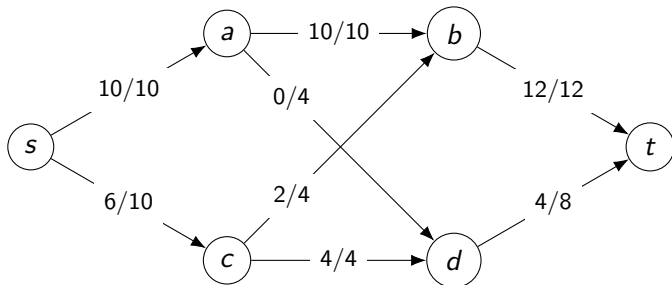
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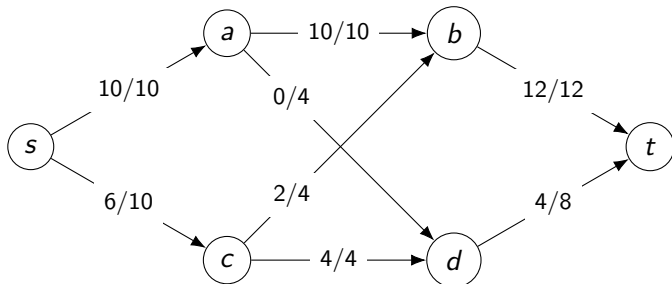
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At this point, there are no more directed paths where all arcs are below capacity. But is this the maximum flow?

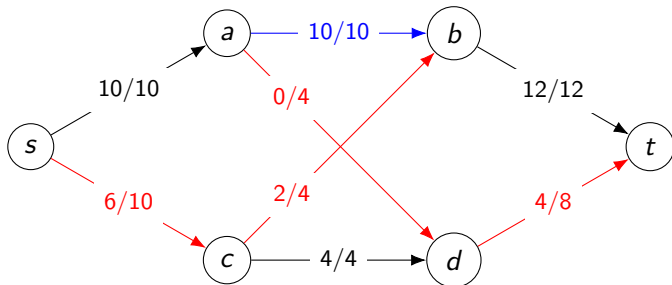
A further improvement

If we redirect some $a \rightarrow b \rightarrow t$ flow to go $a \rightarrow d \rightarrow t$, we can send more flow along the path $s \rightarrow c \rightarrow d \rightarrow t$...



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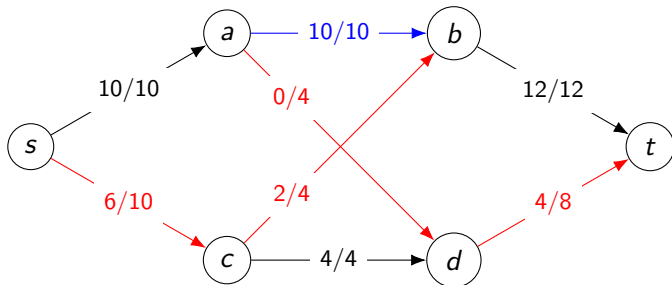
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Increase flow along **red edges**, decrease flow along **blue edge**.

Note: $s \rightarrow c \rightarrow b \leftarrow a \rightarrow d \rightarrow t$ is *almost* a directed path.

Augmenting paths

Definition

Given a network (N, A) and a feasible flow \mathbf{x} , an augmenting path for \mathbf{x} is a sequence of nodes

$$s = v_0, v_1, v_2, \dots, v_k, v_{k+1} = t$$

such that for each pair v_i, v_{i+1} :

- either $e = (v_i, v_{i+1})$ is an arc below capacity
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The sequence

$$s \rightarrow c \rightarrow b \leftarrow a \rightarrow d \rightarrow t$$

we found on the previous slide was an augmenting path.

Using an augmenting path to improve \mathbf{x}

To augment a feasible flow \mathbf{x} along an augmenting path:

- 1 Let $\delta > 0$ be the largest value such that
 - $x_e \leq c_e - \delta$ for all forward arcs on the path;
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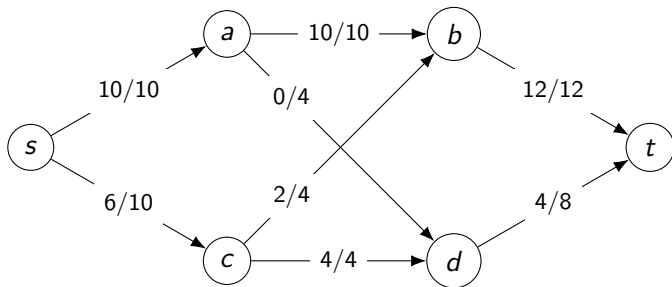
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When we do this, flow is still conserved at internal nodes of the augmenting path. There are four possible cases:

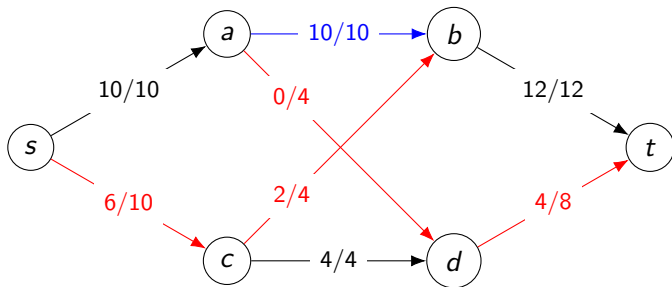
$$\begin{array}{cc} \dots \xrightarrow{+\delta} p \xrightarrow{+\delta} \dots & \dots \xrightarrow{+\delta} q \xleftarrow{-\delta} \dots \\ \dots \xleftarrow{-\delta} r \xrightarrow{+\delta} \dots & \dots \xleftarrow{-\delta} s \xleftarrow{-\delta} \dots \end{array}$$

Example of augmenting



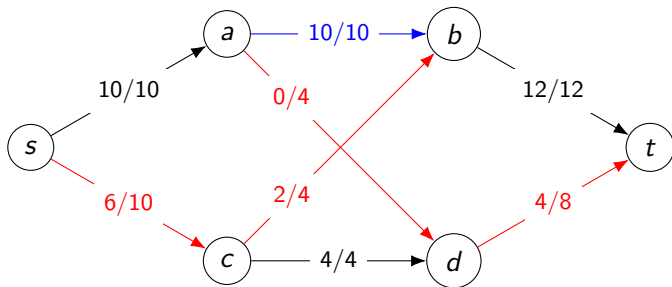
- 1 Find the augmenting path.

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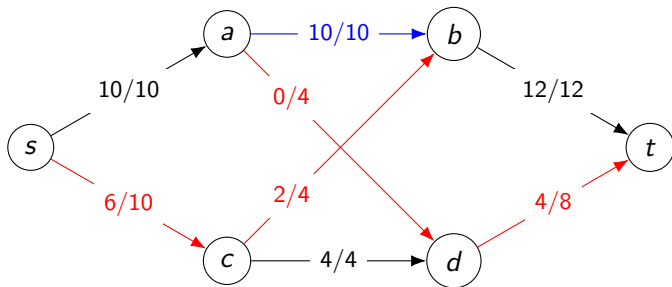
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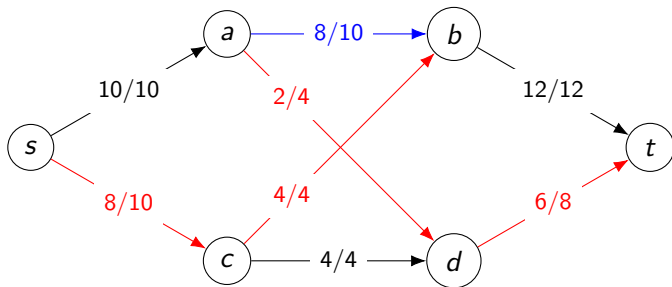
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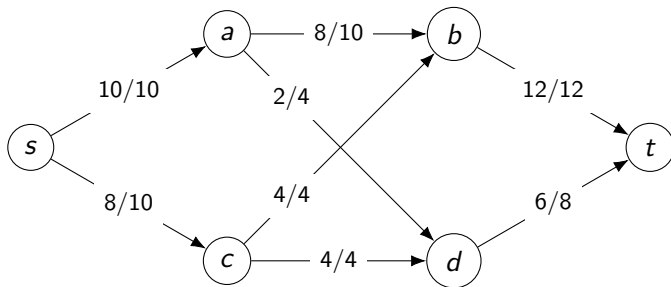
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We define a *residual graph* to help us find augmenting paths.

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- For each arc $(i, j) \in A$ with $x_{ij} > 0$, a “backward” arc (j, i) with residual capacity x_{ij} .

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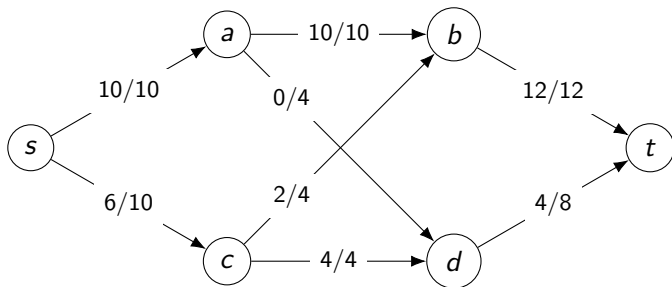
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Idea: augmenting paths for \mathbf{x} are directed paths in the residual graph.

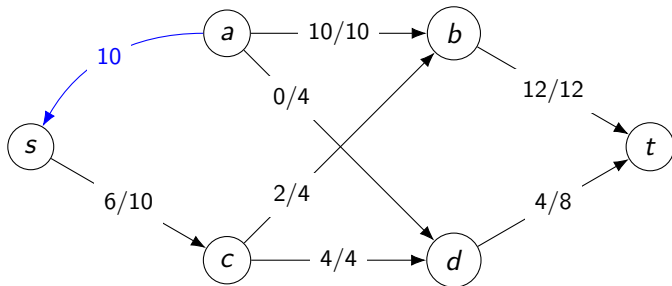
Residual graph example

We construct the residual graph for our next-to-last feasible flow:



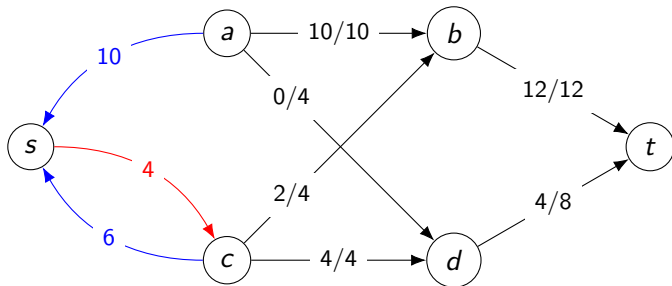
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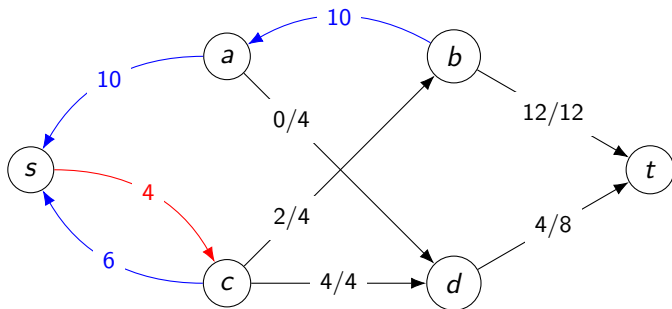
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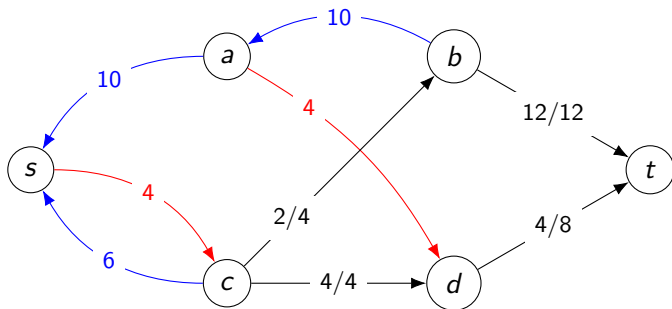
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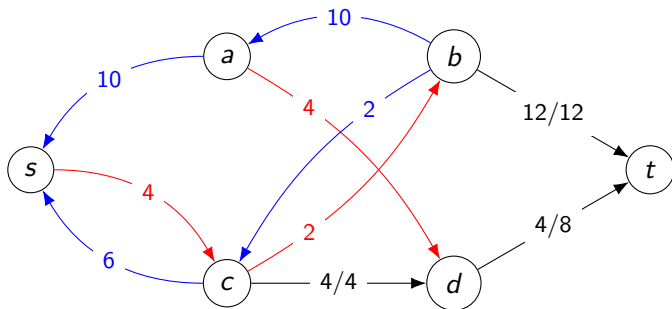
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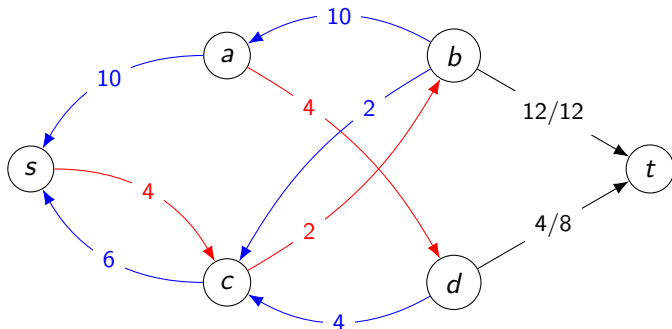
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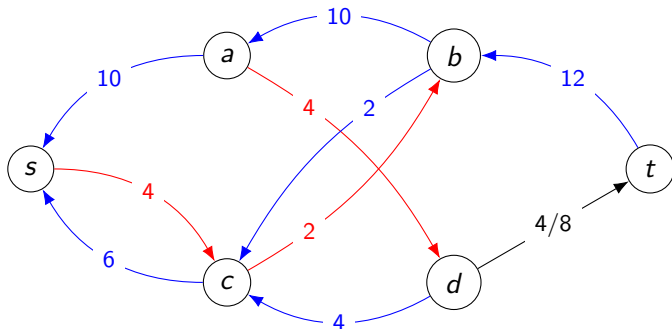
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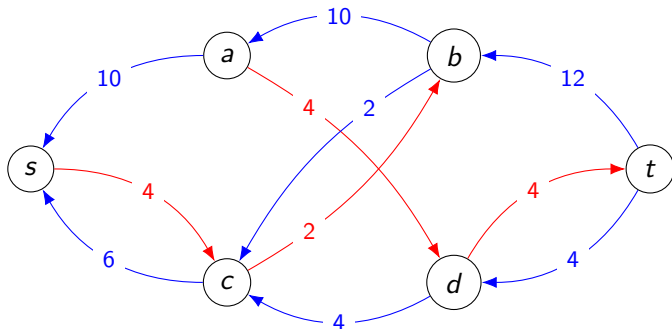
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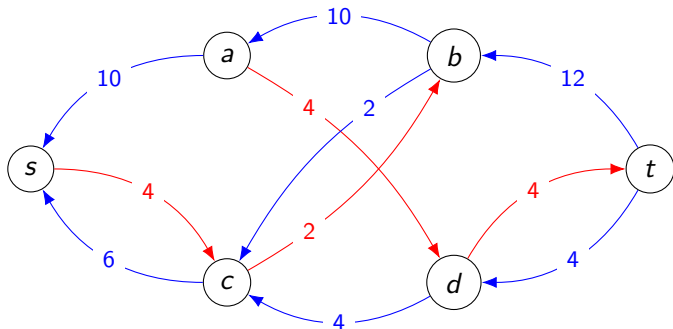
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We can find the augmenting path $s \rightarrow b \leftarrow a \rightarrow d \rightarrow t$ by following only *forward* arrows (of either color) in the residual graph; $\delta = 2$ is the smallest number along those arrows.